

Digital Filters 190529

1 a) Group delay: $T_g(\omega T) = -\frac{\partial \phi(\omega T)}{\partial \omega}$ (or $-\frac{\partial \phi(\omega T)}{\partial (\omega T)}$)

Phase delay: $T_p(\omega T) = -\frac{\phi(\omega T)}{\omega}$ (or $-\frac{\phi(\omega T)}{\omega T}$)

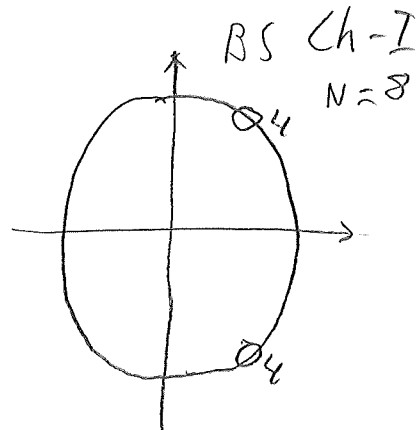
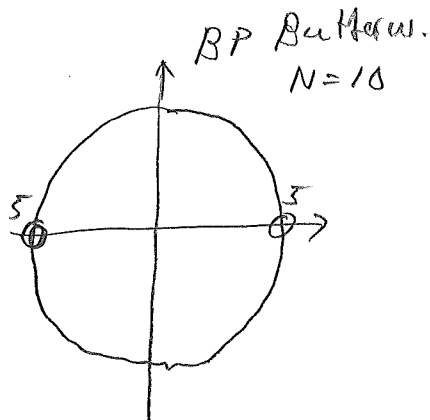
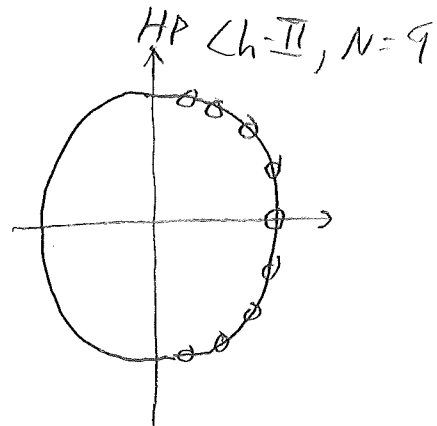
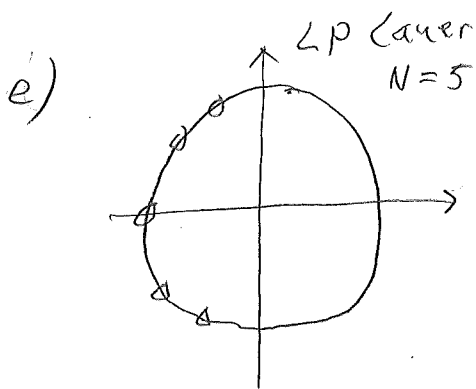
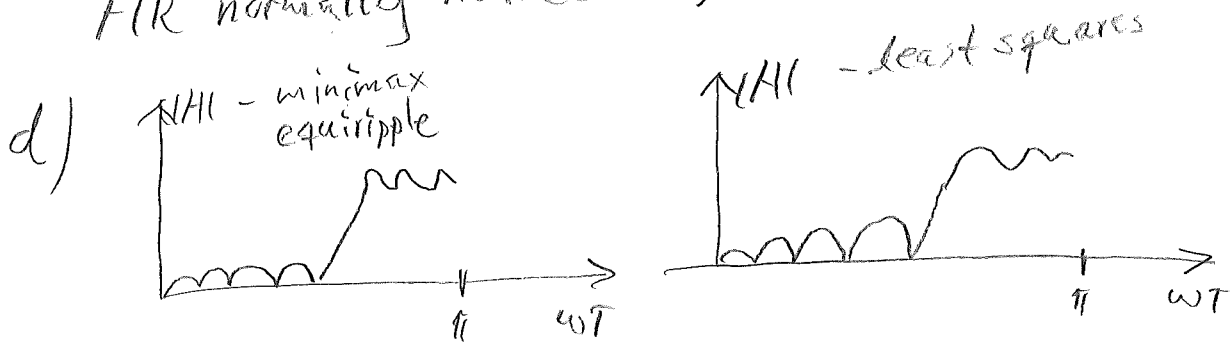
b) Stable filter under finite arithmetic conditions
Recovers after disturbance, no parasitic oscillations

c) Recursive - output computed using input samples and previous output samples

Nonrecursive - output computed using only input samples

IIR always recursive

FIR normally nonrecursive, can be recursive



2) Edges of analog filter $\angle \frac{z}{T} = 1$ for simplicity)

$$\omega_{ac} = \tan\left(\frac{\omega_c T}{2}\right) = 0.207 \quad \omega_{as} \equiv \tan\left(\frac{\omega_s T}{2}\right) = 1$$

$$\frac{\omega_{as}}{\omega_{ac}} = 4.82 \Rightarrow$$

Filter order $N = 3$

$12 \leq \theta \leq 16$ select $\theta = 14$

Normalized zeros: $\pm j 4.7352$, one at $s = \infty$

poles: -1.0012

$-0.4633 \pm j 1.2119$

Denormalized zeros $\pm j 0.9848$, one at $s = \infty$

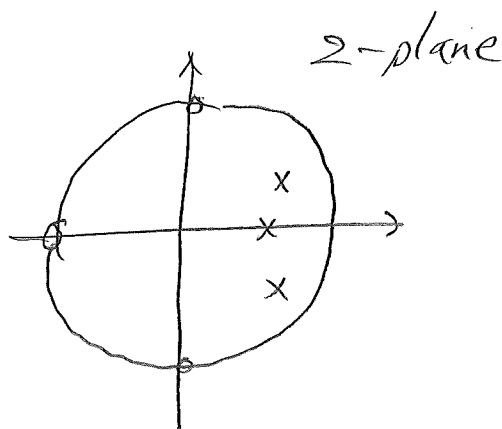
Multi. by ω_{ac} poles -0.2073

$-0.09599 \pm j 0.2510$

$$s \rightarrow z \approx \frac{1+s}{1-s}$$

zeros: $0.01536 \pm j 0.9999$
 -1.0000

poles: 0.6565
 $0.7340 \pm j 0.3971$



3) Edges et analog reference filter

$\omega_{arc} = \tan\left(\frac{\omega_{pass}}{2}\right) = 3.078$, $\omega_{ars} = \tan\left(\frac{\omega_{stop}}{2}\right) = 1.171$

HP \rightarrow LP spec. $\Omega_{arc} = \frac{\omega_F^2}{\omega_{arc}} = \left| \text{select } \omega_F^2 = \omega_{arc} \right| = 1$

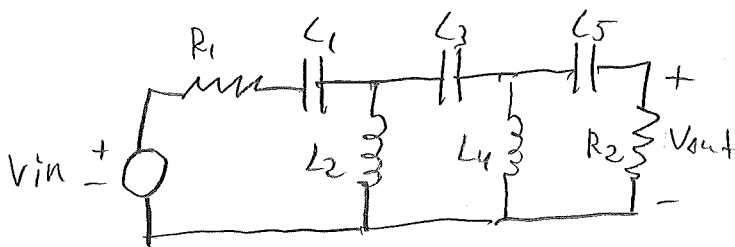
$\Omega_{ars} = \frac{\omega_F^2}{\omega_{ars}} = \frac{\omega_{arc}}{\omega_{ars}} = 2.629$

$\frac{\Omega_{ars}}{\Omega_{arc}} = 2.629 \Rightarrow$ Filter order $N = 5$

Normalized elem. values $L'_1 = L'_5 = 1.7058$, $L'_3 = 2.5408$
 $C'_2 = C'_4 = 1.2296$

Denormalize with $R=1$, $\Omega_{arc}=1 \Rightarrow L=L'$, $C=C'$
 ($=R_1=R_2=1$)

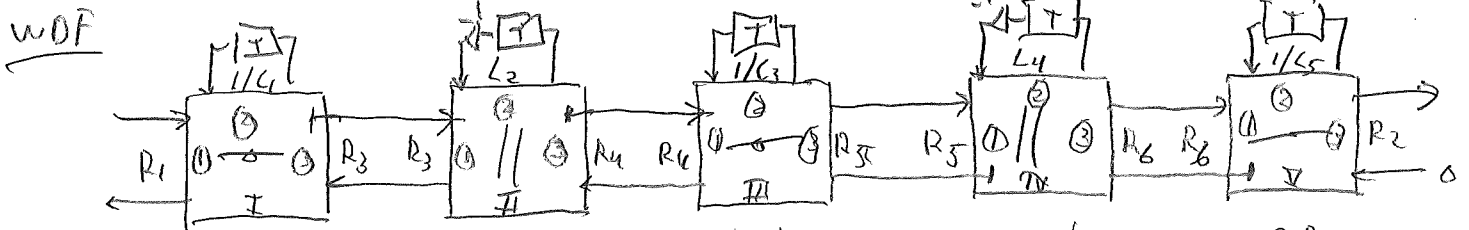
LP \rightarrow HP: $\frac{L}{s} \rightarrow \frac{1}{s^2 L} \Rightarrow$
 $\frac{C}{s} \rightarrow \frac{1}{s^2 C}$



$L_2 = L_4 = \frac{1}{\omega_F^2 L_2} = 0.2642$

$C_1 = C_5 = \frac{1}{\omega_F^2 C_1} = 0.11905$

$L_3 = \frac{1}{\omega_F^2 L_3} = 0.1279$, $R_1 = R_2 = 1$



I: $R_3 = R_1 + \frac{1}{C_1} = 6.2499$

$\alpha_1 = \frac{2R_1}{R_1 + 1/C_2 + R_3} = 0.1600$

$\alpha_2 = 1 - \alpha_1 = 0.8400$

$\alpha_3 = 1$

II: $R_4 = \frac{1}{1/R_3 + 1/L_2} = 0.2535$

$\alpha_1 = \frac{2/R_3}{1/R_3 + 1/L_2 + 1/R_4} = 0.04057$

$\alpha_2 = 1 - \alpha_1 = 0.95943$

$\alpha_3 = 1$

III: $\alpha_1 = \frac{2R_4}{R_4 + 1/C_3 + R_5} = 0.06089$

$\alpha_2 = 2 - \alpha_1 - \alpha_3 = 1.8782$

$\alpha_3 = \alpha_1 = 0.06089$

$R_4 = R_5$

IV: $R_5 = R_4$, $\alpha_1 = 1$

$\alpha_2 = 0.95943$

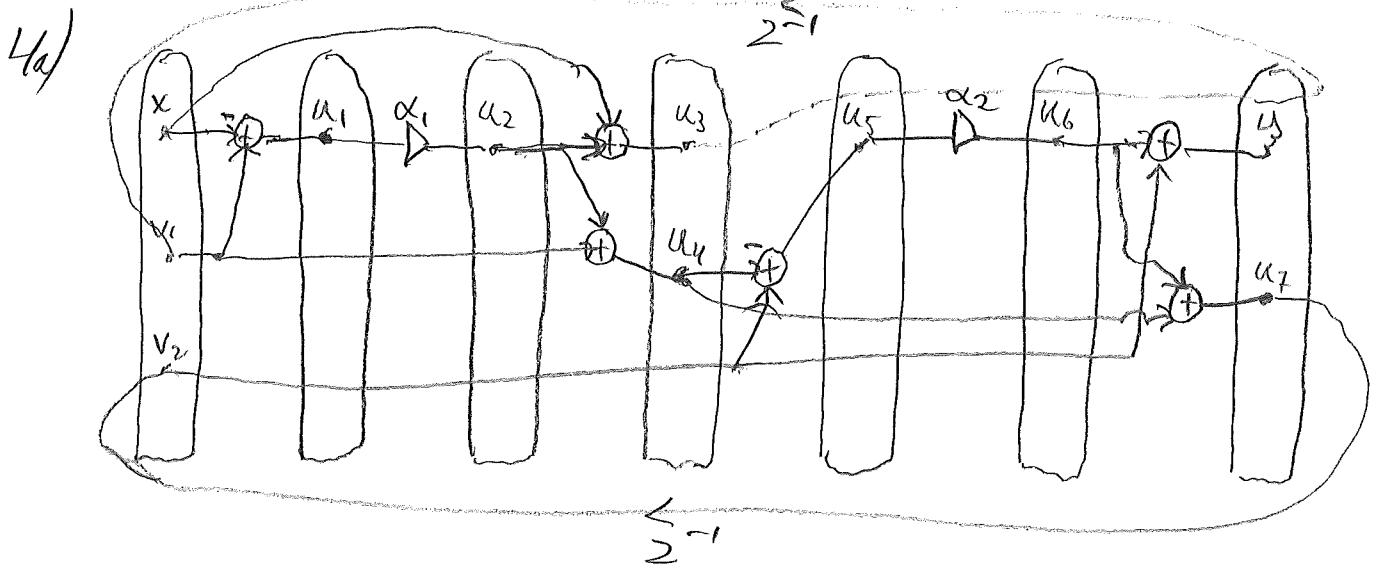
$\alpha_3 = 0.04057$

V: $R_6 = R_3$, $\alpha_1 = 1$

$\alpha_2 = 0.7520$

$\alpha_3 = 0.2480$

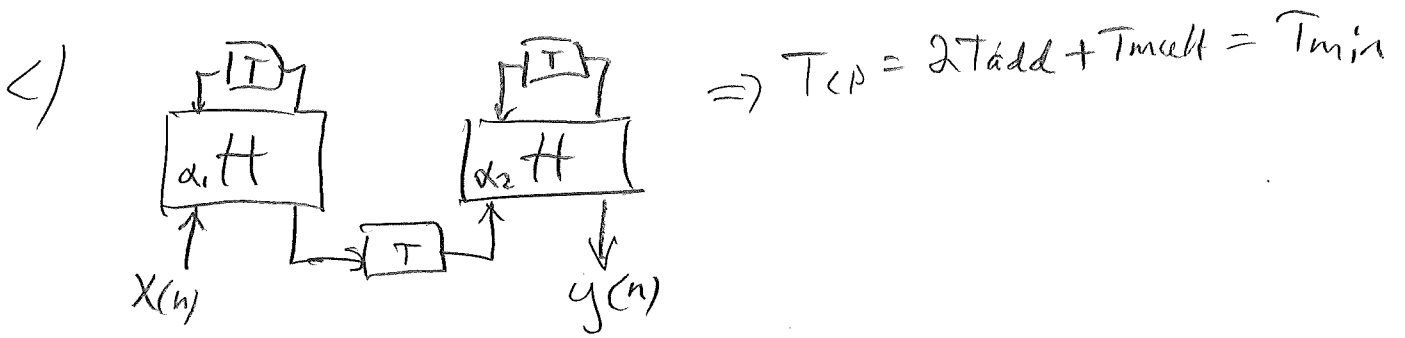
(Symmetry with I)



b)

$$T_{CP} = 4T_{add} + 2T_{mult}$$

$$T_{min} = 2T_{add} + T_{mult}$$



5a) $\frac{N}{2} + 1$ uncorrelated noise sources, propagate directly to the output ($g(n) = \delta(n)$)

$$\Rightarrow \text{Noise variance (average power)} P_{ge} = \left(\frac{N}{2} + 1\right) \cdot \frac{Q^2}{12}$$

$$= \left(\frac{20}{2} + 1\right) \cdot \frac{(2^{-12})^2}{12}$$

$$= 5.464 \times 10^{-28}$$

b) Inputs to mult. scaled by mult. the input $x(n)$ by $c_1 = \frac{1}{2}$ ($c_1 = \frac{1}{\sum_n |h_1(n)|} = \frac{1}{2}$), $f_1(n) = \delta(n) + \delta(n-1)$
 Impulse response from $x(n)$ to the input of mult $h(z)$, $z=0, \dots, \frac{N}{2}$)

Output $y(n)$ scaled by mult. the original mult $h(n)$

$$\text{by } c_2 = \frac{1}{c_1 \cdot \sum_{n=0}^N |h(n)|} = \frac{1/c_1}{(h(\frac{N}{2}) + 2 \cdot \sum_{n=0}^{\frac{N}{2}-1} |h(n)|)}$$

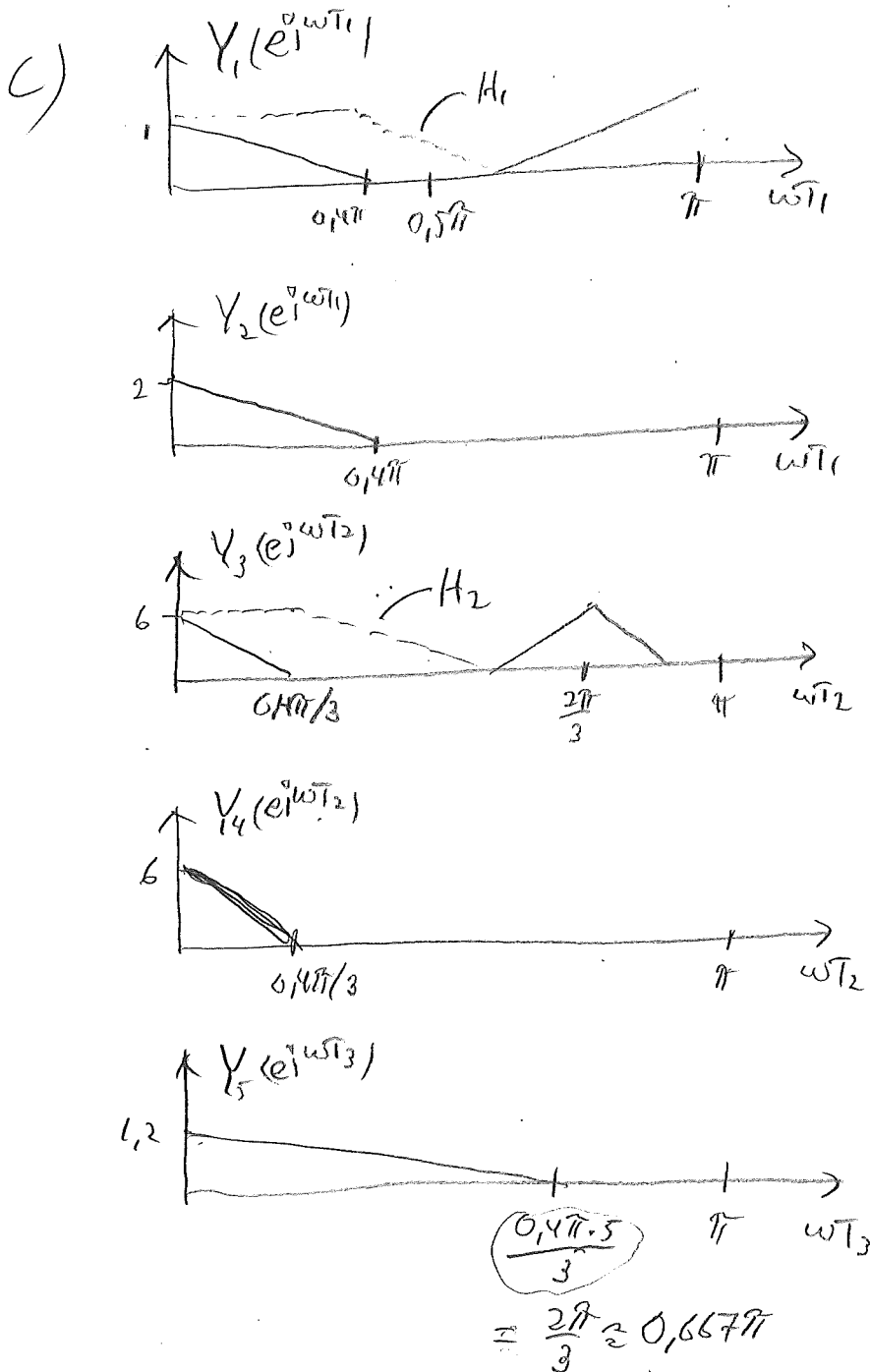
Due to scaling above

$$= \frac{2}{11 + 2 \sum_{n=0}^9 (n+1)} = \frac{2}{11 + 2 \cdot 55} = \frac{2}{121} \approx 0.01653$$

6a) Interp. factor = $2 \times 3/5 = 1.2$

b) H_1 : Edges $0,4\pi, 0,6\pi$, Gain 2

H_2 : Edges $\frac{0,4\pi}{3}, \frac{2\pi}{3} - \frac{0,4\pi}{3} = \frac{1,6\pi}{3}$, Gain = 3



7d) For all structures: N delay elements required

Direct form: Type I, II, IV: $N+1$ mult
III: $N-1$ mult

Linear-phase direct form: Type I: $\frac{N+1}{2}$ mult
II, IV: $\frac{N+1}{2}$ mult
III: $\frac{N}{2}$ mult

↳ Type III & IV: $H(e^{j\omega T}) = j \cdot e^{-j\omega T \cdot N/2} \cdot H_R(\omega T)$

Cascade of III & IV \Rightarrow (since $j \cdot j = -1$)

$$H(e^{j\omega T}) = e^{-j\omega T(N_3+N_4)/2} H_R(\omega T)$$

$$\text{where } H_R(\omega T) = -H_R^{(3)}(\omega T) \cdot H_R^{(4)}(\omega T)$$

\therefore The result is a Type II filter due to
and N_3+N_4 is odd when N_3 is even and N_4 odd